

運動曲面上の接ベクトル場の間の内積  
 束縛力(正運動曲面上)の性質

$\tilde{A}^{\alpha} = \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \dot{q}^{\mu}$  を示すには、次の Christoffel 記号の性質を利用する:

$$\tilde{T}_{\beta\gamma}^{\alpha} = \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\beta}} \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\gamma}} T_{\beta\gamma}^{\alpha} + \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \frac{\partial^2 \dot{q}^{\mu}}{\partial \dot{q}^{\beta} \partial \dot{q}^{\gamma}} \quad \text{--- (d)}$$

$$\frac{dQ^{\alpha}}{dt} = \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \frac{d\dot{q}^{\mu}}{dt} \left( \text{一般速度} \quad \left( \frac{d\dot{q}^{\mu}}{dt} \right) \text{ は接ベクトル場の成り立ちから} \right)$$

$$\frac{d^2 Q^{\alpha}}{dt^2} = \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \frac{d^2 \dot{q}^{\mu}}{dt^2} + \frac{\partial^2 Q^{\alpha}}{\partial \dot{q}^{\mu} \partial \dot{q}^{\nu}} \frac{d\dot{q}^{\mu}}{dt} \frac{d\dot{q}^{\nu}}{dt}$$

$$\tilde{A}^{\alpha} = \frac{d^2 Q^{\alpha}}{dt^2} + \tilde{T}_{\beta\gamma}^{\alpha} \frac{d\dot{q}^{\beta}}{dt} \frac{d\dot{q}^{\gamma}}{dt}$$

$$= \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \frac{d^2 \dot{q}^{\mu}}{dt^2} + \frac{\partial^2 Q^{\alpha}}{\partial \dot{q}^{\mu} \partial \dot{q}^{\nu}} \frac{d\dot{q}^{\mu}}{dt} \frac{d\dot{q}^{\nu}}{dt} + \tilde{T}_{\beta\gamma}^{\alpha} \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \frac{d\dot{q}^{\mu}}{dt} \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\beta}} \frac{d\dot{q}^{\beta}}{dt}$$

$$= \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \frac{d^2 \dot{q}^{\mu}}{dt^2} + \left( \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\nu}} \tilde{T}_{\beta\gamma}^{\alpha} + \frac{\partial^2 Q^{\alpha}}{\partial \dot{q}^{\mu} \partial \dot{q}^{\nu}} \right) \frac{d\dot{q}^{\mu}}{dt} \frac{d\dot{q}^{\nu}}{dt}$$

$$\frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\nu}} \left( \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\nu}} \tilde{T}_{\beta\gamma}^{\alpha} + \frac{\partial^2 Q^{\alpha}}{\partial \dot{q}^{\mu} \partial \dot{q}^{\nu}} \right)$$

$$= \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\nu}} (\dots)$$

$$= \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} T_{\mu\nu}^{\alpha} \quad \left[ \text{① } \tilde{T}_{\beta\gamma}^{\alpha} = T_{\beta\gamma}^{\alpha}, \text{ 後者は代入して成り立つ} \right]$$

$$= \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \left( \frac{d^2 \dot{q}^{\mu}}{dt^2} + T_{\mu\nu}^{\alpha} \frac{d\dot{q}^{\mu}}{dt} \frac{d\dot{q}^{\nu}}{dt} \right) = \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \tilde{A}^{\mu}$$

② の証明:

$$\tilde{T}_{\beta\gamma}^{\alpha} = \frac{1}{2} \tilde{g}^{\alpha\mu} \left( \frac{\partial \tilde{g}_{\mu\beta}}{\partial \dot{q}^{\gamma}} + \frac{\partial \tilde{g}_{\mu\gamma}}{\partial \dot{q}^{\beta}} - \frac{\partial \tilde{g}_{\beta\gamma}}{\partial \dot{q}^{\mu}} \right)$$

$$\frac{\partial \tilde{g}_{\mu\beta}}{\partial \dot{q}^{\gamma}} = \frac{\partial}{\partial \dot{q}^{\gamma}} \left( \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\beta}} \frac{\partial \dot{q}^{\nu}}{\partial \dot{q}^{\gamma}} g_{\mu\nu} \right)$$

$$= \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\beta}} \frac{\partial \dot{q}^{\nu}}{\partial \dot{q}^{\gamma}} \frac{\partial g_{\mu\nu}}{\partial \dot{q}^{\gamma}} + g_{\mu\nu} \left( \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\beta}} \frac{\partial^2 \dot{q}^{\nu}}{\partial \dot{q}^{\beta} \partial \dot{q}^{\gamma}} + \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\beta}} \frac{\partial^2 \dot{q}^{\nu}}{\partial \dot{q}^{\gamma} \partial \dot{q}^{\beta}} \right)$$

③ の証明:

$$\tilde{T}_{\beta\gamma}^{\alpha} = \frac{1}{2} \frac{\partial Q^{\alpha}}{\partial \dot{q}^{\mu}} \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\nu}} \frac{\partial \dot{q}^{\nu}}{\partial \dot{q}^{\beta}} \left( \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\gamma}} \frac{\partial \dot{q}^{\nu}}{\partial \dot{q}^{\beta}} \frac{\partial g_{\mu\nu}}{\partial \dot{q}^{\gamma}} + g_{\mu\nu} \left( \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\beta}} \frac{\partial^2 \dot{q}^{\nu}}{\partial \dot{q}^{\beta} \partial \dot{q}^{\gamma}} + \frac{\partial \dot{q}^{\mu}}{\partial \dot{q}^{\beta}} \frac{\partial^2 \dot{q}^{\nu}}{\partial \dot{q}^{\gamma} \partial \dot{q}^{\beta}} \right) \right)$$

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④ ~~の証明: 3v'~~

$$\Gamma_{\alpha\beta\gamma} := \frac{1}{2} \left( \frac{\partial g_{\alpha\beta}}{\partial g^\gamma} + \frac{\partial g_{\alpha\gamma}}{\partial g^\beta} - \frac{\partial g_{\beta\gamma}}{\partial g^\alpha} \right)$$

⑤ ~~の証明: 2v'の~~

「幾何学的運動方程式」の取組を「2」, 書くと,

$$g_{\alpha\beta} \frac{d^2 g^\beta}{dt^2} + \Gamma_{\alpha\beta\gamma} \frac{d g^\beta}{dt} \frac{d g^\gamma}{dt} = F_\alpha, \quad \text{--- ①}$$

$$\Gamma_{\alpha\beta\gamma} := \frac{1}{2} \left( \frac{\partial g_{\alpha\beta}}{\partial g^\gamma} + \frac{\partial g_{\alpha\gamma}}{\partial g^\beta} - \frac{\partial g_{\beta\gamma}}{\partial g^\alpha} \right),$$

$$F_\alpha := \sum_{i=1}^{N_b} F_i \cdot \frac{\partial r_i}{\partial g^\alpha}.$$

運動エネルギー -  $T := \sum_{i=1}^{N_b} \frac{m_i}{2} \| \dot{r}_i \|^2 = \frac{1}{2} g_{\alpha\beta} \dot{g}^\alpha \dot{g}^\beta$

||  
 $T(g, \dot{g})$  ( $\dot{g}^\alpha$ ) $_{\alpha}$  の独立変数をとる。

$$\text{① } T_{\text{kin}} = g_{\alpha\beta} \dot{g}^\alpha \dot{g}^\beta + \frac{1}{2} \left( \frac{\partial g_{\alpha\beta}}{\partial g^\gamma} + \frac{\partial g_{\alpha\gamma}}{\partial g^\beta} - \frac{\partial g_{\beta\gamma}}{\partial g^\alpha} \right) \dot{g}^\beta \dot{g}^\gamma$$

$$= \frac{1}{2} (g_{\alpha\beta} \ddot{g}^\alpha \dot{g}^\beta + g_{\alpha\gamma} \dot{g}^\alpha \ddot{g}^\gamma) + \frac{1}{2} \left( \frac{\partial g_{\alpha\beta}}{\partial g^\gamma} \dot{g}^\beta \dot{g}^\gamma + \frac{\partial g_{\alpha\gamma}}{\partial g^\beta} \dot{g}^\alpha \dot{g}^\beta \right)$$

$$- \frac{1}{2} \frac{\partial g_{\beta\gamma}}{\partial g^\alpha} \dot{g}^\beta \dot{g}^\gamma$$

$$= \frac{d}{dt} \left[ \frac{\partial T}{\partial \dot{g}^\alpha} \right] - \frac{\partial T}{\partial g^\alpha}$$

$$= \frac{d}{dt} \left( \frac{\partial T}{\partial \dot{g}^\alpha} \right) - \frac{\partial T}{\partial g^\alpha}$$

$$\therefore \frac{d}{dt} \left( \frac{\partial T}{\partial \dot{g}^\alpha} \right) - \frac{\partial T}{\partial g^\alpha} = F_\alpha, \quad (\alpha = 1, \dots, N),$$

$$T := \frac{1}{2} g_{\alpha\beta} \dot{g}^\alpha \dot{g}^\beta \quad \text{運動エネルギー},$$

$$F_\alpha := \sum_{i=1}^{N_b} F_i \cdot \frac{\partial r_i}{\partial g^\alpha} \quad (\alpha = 1, \dots, N),$$

位置エネルギー  $V(x_1, \dots, x_{N_b})$  の場合

$$F_i = -\frac{\partial V}{\partial x_i} := -\left(\frac{\partial V}{\partial x_i}, \frac{\partial V}{\partial y_i}, \frac{\partial V}{\partial z_i}\right)$$

$$\begin{aligned} F_a &= -\sum_{i=1}^{N_b} \left( \frac{\partial V}{\partial x_i} \frac{\partial x_i}{\partial q^a} + \frac{\partial V}{\partial y_i} \frac{\partial y_i}{\partial q^a} + \frac{\partial V}{\partial z_i} \frac{\partial z_i}{\partial q^a} \right) \\ &= -\frac{\partial V}{\partial q^a} \end{aligned}$$

$$\frac{d}{dt} \left( \frac{\partial T}{\partial \dot{q}^a} \right) - \frac{\partial T}{\partial q^a} = -\frac{\partial V}{\partial q^a}$$

$$\frac{\partial V}{\partial q^a} = 0 \quad \forall a$$

Lagrange 運動方程式

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}^a} \right) - \frac{\partial L}{\partial q^a} = 0 \quad (a=1, \dots, N)$$

$$L := T - V \quad \text{Lagrangian}$$

... 座標  $q^a$  の変換  $\tilde{q}^a$  の場合

2. 位置ベクトル  $\mathbf{r}$  とポテンシャル  $V(x_1, \dots, x_{N_b})$  の場合

$$\mathbf{F}_i = - \frac{\partial V}{\partial \mathbf{r}_i} := - \left( \frac{\partial V}{\partial x_i}, \frac{\partial V}{\partial y_i}, \frac{\partial V}{\partial z_i} \right)$$

$$\begin{aligned} \mathbf{F} &= - \sum_{i=1}^{N_b} \left( \frac{\partial V}{\partial x_i} \frac{\partial x_i}{\partial \mathbf{r}^\alpha} + \frac{\partial V}{\partial y_i} \frac{\partial y_i}{\partial \mathbf{r}^\alpha} + \frac{\partial V}{\partial z_i} \frac{\partial z_i}{\partial \mathbf{r}^\alpha} \right) \\ &= - \frac{\partial V}{\partial \mathbf{r}^\alpha} \end{aligned}$$

$$\frac{d}{dt} \left( \frac{\partial T}{\partial \dot{\mathbf{r}}^\alpha} \right) - \frac{\partial T}{\partial \mathbf{r}^\alpha} = - \frac{\partial V}{\partial \mathbf{r}^\alpha}$$

$$\frac{\partial V}{\partial \mathbf{r}^\alpha} = 0 \quad \forall \alpha$$

Lagrange 運動方程式

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{\mathbf{r}}^\alpha} \right) - \frac{\partial L}{\partial \mathbf{r}^\alpha} = 0 \quad (\alpha = 1, \dots, N)$$

$$L := T - V \quad \text{Lagrangian.}$$

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2022/12/2 (金)

Christoffel 記号, 慣性テンソル, 証明.

$$T_{\alpha\beta\gamma} := \frac{1}{2} \left( \frac{\partial g_{\alpha\beta}}{\partial x^\gamma} + \frac{\partial g_{\alpha\gamma}}{\partial x^\beta} - \frac{\partial g_{\beta\gamma}}{\partial x^\alpha} \right)$$

の 慣性テンソル の 証明.

$$\tilde{g}_{\alpha\beta} = \frac{\partial g_{\alpha\mu}}{\partial x^\beta} \frac{\partial x^\mu}{\partial x^\beta} \tilde{g}_{\mu\lambda}$$

$$\frac{\partial \tilde{g}_{\alpha\beta}}{\partial x^\gamma} = \frac{\partial}{\partial x^\gamma} \left( \frac{\partial g_{\alpha\mu}}{\partial x^\beta} \frac{\partial x^\mu}{\partial x^\beta} \frac{\partial x^\nu}{\partial x^\beta} \right)$$

$$\frac{\partial \tilde{g}_{\alpha\beta}}{\partial x^\gamma} = \frac{\partial g_{\alpha\mu}}{\partial x^\beta} \frac{\partial x^\mu}{\partial x^\beta} \frac{\partial x^\nu}{\partial x^\beta} + \tilde{g}_{\alpha\lambda} \frac{\partial g_{\mu\nu}}{\partial x^\beta} \frac{\partial x^\mu}{\partial x^\beta} \frac{\partial x^\nu}{\partial x^\beta} + \tilde{g}_{\alpha\lambda} \frac{\partial g_{\mu\nu}}{\partial x^\beta} \frac{\partial x^\mu}{\partial x^\beta} \frac{\partial x^\nu}{\partial x^\beta} \quad (1)$$

$$\frac{\partial \tilde{g}_{\alpha\beta}}{\partial x^\beta} = \frac{\partial g_{\alpha\mu}}{\partial x^\beta} \frac{\partial x^\mu}{\partial x^\beta} \frac{\partial x^\nu}{\partial x^\beta} + \tilde{g}_{\alpha\lambda} \frac{\partial g_{\mu\nu}}{\partial x^\beta} \frac{\partial x^\mu}{\partial x^\beta} \frac{\partial x^\nu}{\partial x^\beta} + \tilde{g}_{\alpha\lambda} \frac{\partial g_{\mu\nu}}{\partial x^\beta} \frac{\partial x^\mu}{\partial x^\beta} \frac{\partial x^\nu}{\partial x^\beta} \quad (2)$$

$$\frac{\partial \tilde{g}_{\alpha\beta}}{\partial x^\alpha} = \frac{\partial g_{\alpha\mu}}{\partial x^\beta} \frac{\partial x^\mu}{\partial x^\beta} \frac{\partial x^\nu}{\partial x^\beta} + \tilde{g}_{\alpha\lambda} \frac{\partial g_{\mu\nu}}{\partial x^\beta} \frac{\partial x^\mu}{\partial x^\beta} \frac{\partial x^\nu}{\partial x^\beta} + \tilde{g}_{\alpha\lambda} \frac{\partial g_{\mu\nu}}{\partial x^\beta} \frac{\partial x^\mu}{\partial x^\beta} \frac{\partial x^\nu}{\partial x^\beta} \quad (3)$$

$$(1) + (2) - (3) \times \frac{1}{2} \quad \alpha \neq \beta$$



$$\begin{aligned} \tilde{T}_{\mu\nu} &= \frac{1}{2} \left( \frac{\partial g_{\mu\lambda}}{\partial x^\sigma} \frac{\partial g^{\lambda\rho}}{\partial x^\alpha} \frac{\partial x^\sigma}{\partial x^\beta} + \frac{\partial g_{\mu\lambda}}{\partial x^\rho} \frac{\partial g^{\lambda\sigma}}{\partial x^\alpha} \frac{\partial x^\rho}{\partial x^\beta} - \frac{\partial g_{\mu\lambda}}{\partial x^\alpha} \frac{\partial g^{\lambda\sigma}}{\partial x^\rho} \frac{\partial x^\sigma}{\partial x^\beta} \right. \\ &\quad \left. + 2 g_{\mu\lambda} \frac{\partial g^{\lambda\sigma}}{\partial x^\alpha} \frac{\partial^2 x^\sigma}{\partial x^\rho \partial x^\tau} \right) \\ &= \frac{1}{2} \left( \frac{\partial g_{\mu\lambda}}{\partial x^\sigma} \frac{\partial g^{\lambda\rho}}{\partial x^\alpha} \frac{\partial x^\sigma}{\partial x^\beta} \frac{\partial x^\rho}{\partial x^\tau} + \frac{\partial g_{\mu\lambda}}{\partial x^\rho} \frac{\partial g^{\lambda\sigma}}{\partial x^\alpha} \frac{\partial x^\rho}{\partial x^\beta} \frac{\partial x^\sigma}{\partial x^\tau} \right. \\ &\quad \left. - \frac{\partial g_{\mu\lambda}}{\partial x^\alpha} \frac{\partial g^{\lambda\sigma}}{\partial x^\rho} \frac{\partial x^\sigma}{\partial x^\beta} \frac{\partial x^\rho}{\partial x^\tau} \right) + g_{\mu\lambda} \frac{\partial g^{\lambda\sigma}}{\partial x^\alpha} \frac{\partial^2 x^\sigma}{\partial x^\rho \partial x^\tau} \\ &= \frac{1}{2} \frac{\partial g^{\lambda\sigma}}{\partial x^\alpha} \frac{\partial x^\sigma}{\partial x^\beta} \frac{\partial x^\rho}{\partial x^\tau} \left( \frac{\partial g_{\mu\lambda}}{\partial x^\sigma} + \frac{\partial g_{\mu\lambda}}{\partial x^\rho} - \frac{\partial g_{\mu\lambda}}{\partial x^\alpha} \right) + g_{\mu\lambda} \frac{\partial g^{\lambda\sigma}}{\partial x^\alpha} \frac{\partial^2 x^\sigma}{\partial x^\rho \partial x^\tau} \end{aligned}$$

24.4)

$$\begin{aligned} \tilde{T}_{\mu\nu} &= g^{\alpha\sigma} \tilde{T}_{\sigma\rho\tau} = \frac{\partial g^\alpha}{\partial x^\sigma} \left( \frac{\partial g_{\mu\lambda}}{\partial x^\sigma} \frac{\partial x^\sigma}{\partial x^\beta} \frac{\partial x^\rho}{\partial x^\tau} \Gamma_{\lambda\sigma\mu} + g_{\mu\lambda} \frac{\partial g^{\lambda\sigma}}{\partial x^\alpha} \frac{\partial^2 x^\sigma}{\partial x^\rho \partial x^\tau} \right) \\ &= \frac{\partial g^\alpha}{\partial x^\sigma} \frac{\partial x^\sigma}{\partial x^\beta} \frac{\partial x^\rho}{\partial x^\tau} \Gamma_{\lambda\sigma\mu} + \frac{\partial g^\alpha}{\partial x^\sigma} g_{\mu\lambda} \frac{\partial g^{\lambda\sigma}}{\partial x^\alpha} \frac{\partial^2 x^\sigma}{\partial x^\rho \partial x^\tau} \\ &= \frac{\partial g^\alpha}{\partial x^\sigma} \frac{\partial x^\sigma}{\partial x^\beta} \frac{\partial x^\rho}{\partial x^\tau} \Gamma_{\lambda\sigma\mu} + \frac{\partial g^\alpha}{\partial x^\sigma} \frac{\partial^2 x^\sigma}{\partial x^\rho \partial x^\tau} \end{aligned} \quad \square$$